

Group 18: The Dark Knights

Client Meeting 3: Prototype 1

Brayden, Adam, Jordan, Rami, and Hala





Goals of Client Meeting 3:

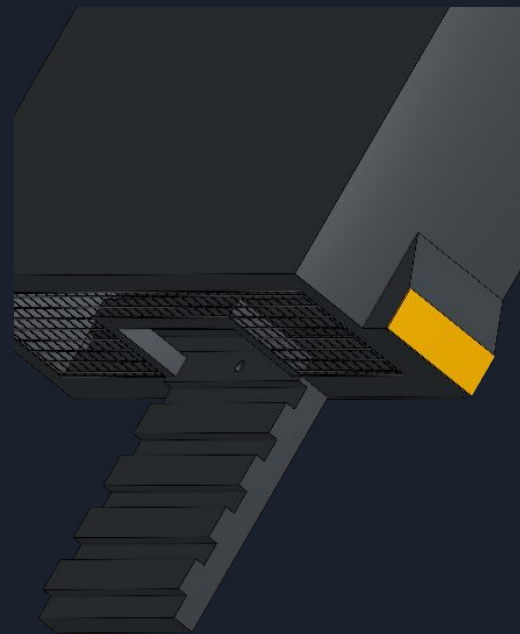
- Show our first prototype to Client and Classmates, which includes our bat box structure, the tracking/storing device and the power and coding functionality.
- Receive feedback from Client and Classmates



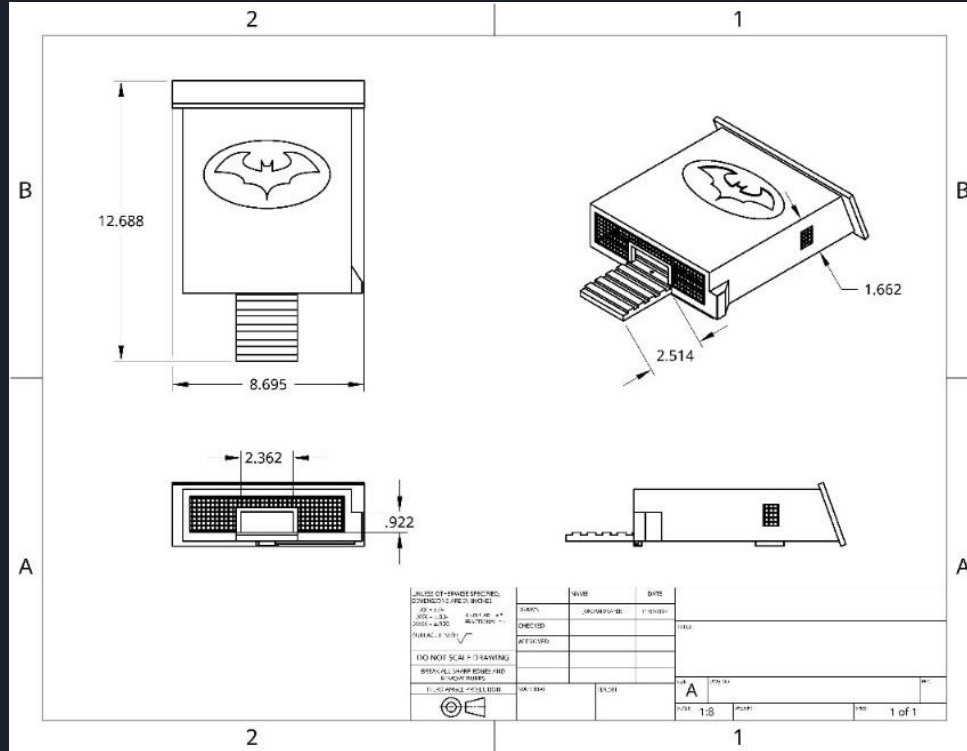
Bat Box Structure

- The following bat box design includes a housing system for tracking devices and a laser sensor, along with an adjusted entrance and square patterned mesh to enhance functionality.
- A small side box holds the tracking system, while a laser setup tracks bats entering the box.
- The box meets all client requirements, with the next steps focussed on creating a laser cutting template.

Bat Box Structure



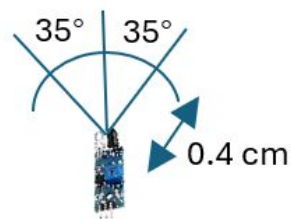
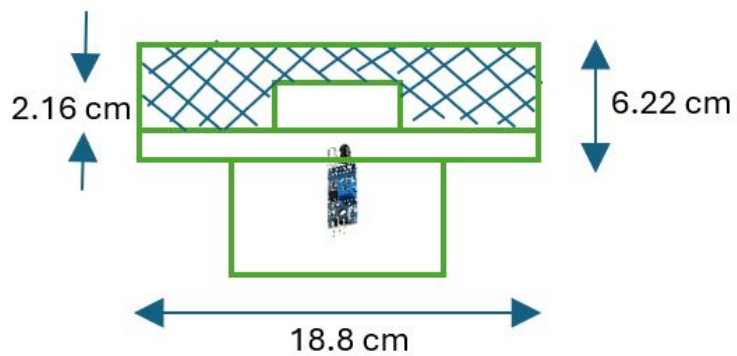
Bat box structure



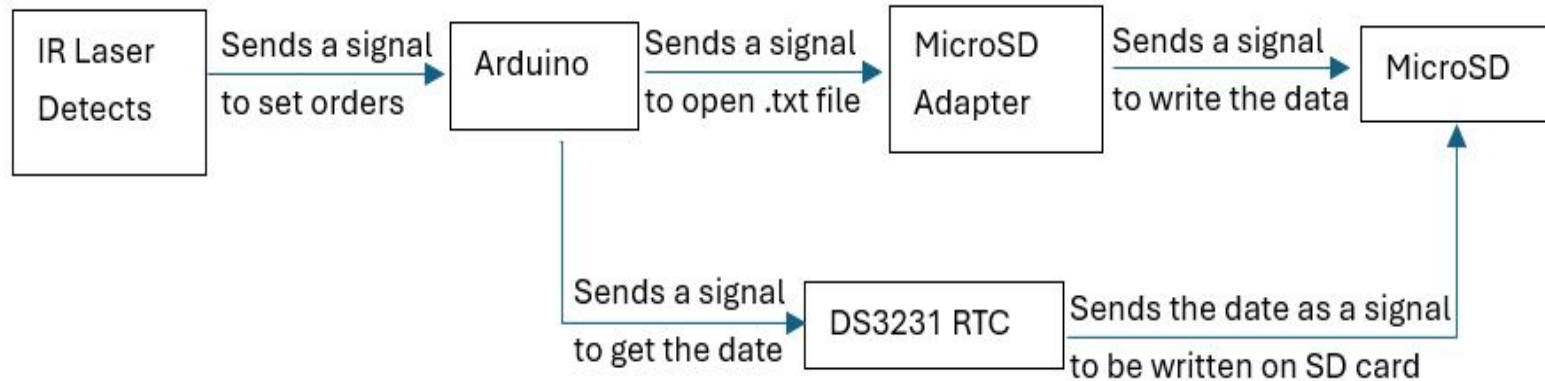


Tracking/Storing Device

- Uses an infrared laser sensor at the entrance to detect and record each bat, storing the data with precise date and time stamps via an Arduino and microSD card.
- Laser sensor is adjusted for optimal detection at 2 cm due to sunlight and bat guano, and a green LED verifies the system's functionality.
- Data is stored in four files on the microSD card over 5 months, tracking daily, monthly, and total bat counts, with the total divided by two to estimate unique bats using the box.



How the different components interact within the tracking system



Power and Coding Functionality

- The system is powered by a 12V AC/DC power supply connected to the Arduino Unos external power input.
- The Arduino board converts 12V to 5V to power the laser sensor, microSD adapter, and RTC module in parallel.
- This setup ensures all components receive the required 5V, aligning with voltage specifications for stable operation.

